# Package: ebmstate (via r-universe)

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|--|
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| Author Rui Costa [aut, cre], Moritz Gerstung [aut], Terry M Therneau [ctb] (author of 'survival', a package from which code parts were copied), Thomas Lumley [ctb] (contributor to 'survival', a package from which code parts were copied), Hein Putter [ctb] (co-author of 'mstate', a package from which code parts were copied), Liesbeth de Wreede [ctb] (co-author of 'mstate', a package from which code parts were copied), Marta Fiocco [ctb] (co-author of 'mstate', a package from which code parts were copied), Ronald Geskus [ctb] (contributor to 'mstate', a package from which code parts were copied) |
| Maintainer Rui Costa <ruibarrigana@hotmail.com></ruibarrigana@hotmail.com>   |
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| Contents   |
| ebmstate-package   |

2 ebmstate-package

|       | boot_coxrfx                           |
|-------|---------------------------------------|
|       | boot_ebmstate                         |
|       | boot_probtrans                        |
|       | CIs_for_target_state                  |
|       | convolute_clockforward                |
|       | convolute_clockreset                  |
|       | CoxRFX                                |
|       | coxrfx_object_sample                  |
|       | cumhazCIs_for_target_transition       |
|       | cumhaz_splines                        |
|       | extract_function                      |
|       | joint_cum_hazard_function             |
|       | loo_ebmstate                          |
|       | MakeInteger                           |
|       | msfit_generic                         |
|       | msfit_object_sample                   |
|       | mstate_data                           |
|       | mstate_data_sample                    |
|       | print.coxrfx                          |
|       | print.msfit                           |
|       | probtrans_by_convolution              |
|       | probtrans_by_convolution_clockforward |
|       | probtrans_by_convolution_clockreset   |
|       | probtrans_ebmstate                    |
|       | probtrans_fft                         |
|       | probtrans_mstate                      |
|       | successful_transitions                |
|       | summary.coxrfx                        |
|       | unique_paths                          |
| Index | 3.                                    |
|       |                                       |

ebmstate-package

Empirical Bayes multi-state Cox model

### Description

This package implements an empirical Bayes, multi-state Cox model. Different groups of regression coefficients can be defined, with coefficients of the same group sharing the same Gaussian prior. It takes as input a data set in 'long format' and generates estimates of relative hazards, cumulative hazard functions and transition probabilities. It relies on packages survival and mstate and incorporates some of their functions to reduce upstream dependency.

boot\_coxrfx 3

#### **Details**

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Type: Package
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#### Author(s)

Rui Costa, Moritz Gerstung

boot\_coxrfx

Bootstrap confidence intervals for regression coefficients

#### **Description**

This function computes 95% highest density bootstrap confidence intervals (non-parametric) for the regression coefficients estimated by CoxRFX.

### Usage

```
boot_coxrfx(
   mstate_data_expanded,
   which_group,
   min_nr_samples = 100,
   output = "CIs",
   ...
)
```

### **Arguments**

mstate\_data\_expanded

Data in 'long format', possibly with 'expanded' covariates (as obtained by run-

ning mstate::expand.covs).

which\_group A character vector with the same meaning as the 'groups' argument of the func-

tion CoxRFX but named (with the covariate names).

min\_nr\_samples The confidence interval of any coefficient is based on a number of bootstrap

samples at least as high as this argument. See details.

output Determines the sort of output. See value.

Further arguments to the CoxRFX function.

4 boot\_ebmstate

#### **Details**

In a given bootstrap sample there might not be enough information to generate estimates for all coefficients. If a covariate has little or no variation in a given bootstrap sample, no estimate of its coefficient will be computed. The present function will keep taking bootstrap samples until every coefficient has been estimated at least min\_nr\_samples times.

#### Value

For each regression coefficient, the confidence intervals and the number of bootstrap samples on which they are based, if the 'output' argument is equal to 'CIs'; if 'output' is equal to 'CIs\_and\_coxrfx\_fits', also the CoxRFX objects for each bootstrap sample.

### Author(s)

Rui Costa

boot\_ebmstate

Bootstrap samples and bootstrap interval estimates

### Description

This function computes bootstrap samples of regression coefficients, cumulative hazard functions, and transition probability functions.

### Usage

```
boot_ebmstate(
   mstate_data = NULL,
   which_group = NULL,
   min_nr_samples = NULL,
   patient_data = NULL,
   initial_state = NULL,
   time_model = NULL,
   backup_file = NULL,
   input_file = NULL,
   coxrfx_args = NULL,
   msfit_args = NULL,
   probtrans_args = NULL)
```

### **Arguments**

mstate\_data A data frame with outcome and covariate data in long format.

which\_group A character vector with the same meaning as the 'groups' argument of the func-

tion CoxRFX but named (with the covariate names).

boot\_probtrans 5

| min_nr_samples | The confidence interval of any coefficient is based on a number of bootstrap samples at least as high as this argument. See details.  |
|----------------|---|
| patient_data   | The covariate data for which the estimates of cumulative hazards and transition probabilities are computed. Must contain: one row of data for each transition, all the covariate columns in the fitted model, and also the 'strata' column. |
| initial_state  | The initial state for which transition probability estimates should be computed   |
| tmat           | $Transition\ matrix\ for\ the\ multi-state\ model,\ as\ obtained\ by\ running\ mstate:: \texttt{transMat}$  |
| time_model     | The model of time-dependency: either 'clockforward' or 'clockreset'.  |
| backup_file    | Path to file. Objects generated while the present function is running are stored in this file. This avoids losing all estimates if and when the algorithm breaks down. See argument input_file.   |
| input_file     | Path to backup_file (see argument backup_file). If this argument is given, all other arguments should be NULL.  |
| coxrfx_args    | Named list with arguments to the CoxRFX function other than Z,surv and groups.  |
| msfit_args     | Named list with arguments to the msfit_generic.coxrfx function other than object,newdata and trans.   |
| probtrans_args | Named list with arguments to the probtrans_ebmstate function other than initia_state,cumhaz and model.  |

#### **Details**

In a given bootstrap sample there might not be enough information to generate estimates for all coefficients. If a covariate has little or no variation in a given bootstrap sample, no estimate of its coefficient will be computed. The present function will keep taking bootstrap samples until every coefficient has been estimated at least min\_nr\_samples times. covariate\_df should only contain the covariates of the model one wishes to estimate.

### Value

A list with: 95% bootstrap intervals for each regression coefficient and for transition probabilities; bootstrap samples of regression coefficients, cumulative hazards and transition probabilities.

### Author(s)

Rui Costa

| boot_probtrans | Bootstrap confidence intervals for transition probabilities |
|----------------|---|
|----------------|---|

### **Description**

Generates 95% highest density bootstrap interval estimates for transition probabilities computed using probtrans\_ebmstate (clock-reset version).

CIs\_for\_target\_state

#### Usage

```
boot_probtrans(coxrfx_fits_boot, patient_data, tmat, initial_state, max_time)
```

#### **Arguments**

coxrfx\_fits\_boot

The list of CoxRFX objects obtained by running boot\_coxrfx.

patient\_data (Single) patient data in 'long format', possibly with 'expanded' covariates (as

obtained by running mstate::expand.covs).

tmat Transition matrix for the multi-state model, as obtained by running mstate::transMat

initial\_state The initial state for which transition probability estimates should be computed

max\_time The maximum time for which estimates should be computed

#### Value

Interval estimates for transition probabilities.

### Author(s)

Rui Costa

#### See Also

```
probtrans_ebmstate; boot_coxrfx; transMat; expand.covs
```

### **Description**

Computes 95% highest density bootstrap confidence intervals for the transition probabilities into target\_state, given a list object with boostrap estimates of transition probabilities into multiple states. This function is not meant to be called by the user.

### Usage

```
CIs_for_target_state(target_state, probtrans_objects_boot)
```

### **Arguments**

target\_state The target state for whose transition probabilties the confidence intervals are computed.

probtrans\_objects\_boot

A list containing bootstrap estimates of transition probabilities.

convolute\_clockforward

### **Details**

Uses function extract\_function.

#### Value

95% highest density bootstrap confidence intervals for the transition probabilities into target\_state.

7

### Author(s)

Rui Costa

#### See Also

```
boot_ebmstate; extract_function.
```

convolute\_clockforward

Convolution function for clock-forward models

### Description

Internal function of probtrans\_by\_convolution\_clockforward. It is written in C++ and is not meant to be called directly by the user.

### Usage

```
convolute_clockforward(
  time_vector,
  diff_vector,
  probtrans_vector_1,
  probtrans_vector_2
)
```

### **Arguments**

```
time_vector, diff_vector, probtrans_vector_1, probtrans_vector_2
Numeric vectors.
```

### Author(s)

Moritz Gerstung & Rui Costa

### See Also

probtrans\_by\_convolution\_clockforward.

8 CoxRFX

convolute\_clockreset Convolution function for clock-reset models

### **Description**

Internal function of probtrans\_by\_convolution\_clockreset. It is written in C++ and is not meant to be called directly by the user.

### Usage

```
convolute_clockreset(time_vector, integrand_1, integrand_2)
```

### **Arguments**

```
time_vector, integrand_1, integrand_2 Numeric vectors.
```

#### Author(s)

Moritz Gerstung & Rui Costa

#### See Also

probtrans\_by\_convolution\_clockreset.

CoxRFX

Empirical Bayes, multi-state Cox model

### **Description**

This function estimates a multi-state Cox model with one or more Gaussian priors imposed on the regression coefficients (see Therneau et al., 2003). Multiple groups of coefficients can be defined: coefficients within a group share the same (possibly unknown) mean and variance. The parameters and hyperparameters are efficiently estimated by an EM-type algorithm built around the function survival::coxph.

### Usage

```
CoxRFX(
   Z,
   surv,
   groups = rep(1, ncol(Z)),
   which.mu = unique(groups),
   tol = 0.001,
   max.iter = 50,
   sigma0 = 0.1,
```

**CoxRFX** 9

```
sigma.hat = c("df", "MLE", "REML", "BLUP"),
  verbose = FALSE,
)
```

#### **Arguments**

| Z         | A data frame consisting of the covariate columns of a data set in 'long format', and two extra columns: one named 'trans', with the transition that each row refers to, and another named 'strata', with the stratum of each transition (transitions belonging to the same stratum are assumed to have the same baseline hazard function). |
|-----------|--|
| surv      | A 'survival' object created with survival::Surv.   |
| groups    | A character or numeric vector whose $i$ th element gives the group of the regression coefficient associated with the $i$ th covariate column of $Z$ (coefficients belonging to the same group share the same Gaussian prior).  |
| which.mu  | A vector with names or numbers of coefficient groups (see argument groups). If the name or number of a group of coefficients is given in this argument, CoxRFX will estimate the mean of its Gaussian distribution; otherwise the mean will be fixed at zero.  |
| tol       | Convergence criterium of the EM algorithm. The algorithm stops unless there is at least one parameter (or hyperparameter) for which it holds that the current estimate differs in absolute terms by more than tol from the previous estimate.  |
| max.iter  | The maximum number of iterations in the EM algorithm.  |
| sigma0    | A vector with the initial value of the variance hyperparameter for each group of coefficients. Or a single value, in case the initial value of the variance hyperparameter is meant to be the same for all groups.   |
| sigma.hat | Which estimator to use for the variance hyperparameters (see details).   |
| verbose   | Gives more output.   |
|           | Further arguments passed to the function survival::coxph.  |

#### **Details**

Different estimators exist for the variance hyperparameters: the default is "df", as used by Perperoglou (2014) and introduced by Schall (1991). Alternatives are MLE, REML, and BLUP, as defined by Therneau et al. (2003). Simulations suggest that the 'df' method is the most accurate.

The model can also be fitted using package coxme; the coxme routine numerically optimises the integrated partial likelihood, which may be more accurate, but is computationally expensive.

### Value

An object of class c(coxrfx, coxph.penal, coxph), which is essentially a coxph object with a few extra fields [the inputs \$groups, \$Z and \$surv, and the hyperparameters \$sigma2 (variances) and \$mu (means)]. See survival::coxph.object.

10 CoxRFX

#### Author(s)

Moritz Gerstung & Rui Costa, extending the work of Terry Therneau et al. in the package survival.

#### References

Terry M Therneau, Patricia M Grambsch & V. Shane Pankratz (2003) Penalized Survival Models and Frailty, Journal of Computational and Graphical Statistics, 12:1, 156-175, http://dx.doi.org/10.1198/1061860031365

A. Perperoglou (2014). Cox models with dynamic ridge penalties on time-varying effects of the covariates. Stat Med, 33:170-80. http://dx.doi.org/10.1002/sim.5921

R. Schall (1991). Estimation in generalized linear models with random effects. Biometrika, 78:719-727. http://dx.doi.org/10.1093/biomet/78.4.719

#### See Also

Package survival survival::coxph.object; survival::Surv; package coxme.

### **Examples**

```
# Fit an empirical Bayes Cox model using
# simulated, illness-death data from 250
# patients ('mstate_data_sample').
#load simulated data
data("mstate_data_sample")
# Set class of 'mstate_data_sample'
class(mstate_data_sample)<-c("data.frame", "msdata")</pre>
# add transition matrix as attribute
tmat < -mstate::transMat(x=list(c(2,3),c(4),c(),c()),
      names=c("health","illness","death",
     "death_after_illness"))
attr(mstate_data_sample, "trans")<-tmat
# expand covariates by transition:
covariates.expanded<-mstate::expand.covs(</pre>
      mstate_data_sample,
      covs=names(mstate_data_sample)
      [!names(mstate_data_sample)%in%c("id", "from",
      "to", "trans", "Tstart", "Tstop", "time", "status",
      "strata")],append=FALSE)
# argument 'Z' of coxrfx
Z<-data.frame(covariates.expanded,</pre>
   trans=mstate_data_sample$trans,
   strata=mstate_data_sample$trans)
# argument 'surv' for a non-homogeneous
# Markov model
surv<-survival::Surv(mstate_data_sample$Tstart,</pre>
```

coxrfx\_object\_sample 11

### **Description**

An RData object containing the model fit obtained by running CoxRFX on the data set mstate\_data\_sample (included in the present package).

### Usage

```
coxrfx_object_sample
```

#### **Format**

An object of class c(coxrfx, coxph.penal, coxph), which is essentially a coxph object with a few extra fields [the inputs \$groups, \$Z, and \$surv, and the hyperparameters \$sigma2 (variances) and \$mu (means)].

### See Also

```
mstate_data_sample; CoxRFX.
```

### **Description**

Computes 95% highest density, non-parametric bootstrap confidence intervals for the cumulative hazard rate functions, given a list of msfit objects with boostrap estimates of cumulative hazard rate functions for multiple transitions. This function is not meant to be called by the user.

12 cumhaz\_splines

#### Usage

```
cumhazCIs_for_target_transition(transition, msfit_objects_boot)
```

#### **Arguments**

transition The transition for which transition confidence intervals are computed. msfit\_objects\_boot

List of msfit objects with boostrap estimates of cumulative hazard rate functions for multiple transitions.

#### Value

95% highest density, non-parametric bootstrap confidence intervals for the cumulative hazard rate functions.

### Author(s)

Rui Costa

#### See Also

boot\_ebmstate.

cumhaz\_splines

Spline approximations of the cumulative hazard functions

### **Description**

Creates a spline approximation for the vector of cumulative hazards of each transition.

### Usage

```
cumhaz_splines(cumhaz)
```

### **Arguments**

cumhaz

An object of class msfit, created by msfit\_generic or msfit.

### **Details**

This function is used by the function probtrans\_by\_convolution. It is not meant to be called by the user.

### Value

A list of estimated cumulative hazard functions (one for each transition).

extract\_function 13

#### Author(s)

Rui Costa

#### See Also

msfit\_generic; msfit; probtrans\_by\_convolution.

extract\_function

Ancillary function to boot\_ebmstate.

### **Description**

Extracts the bootstrap estimates of transition probabilities for target state 'tstate' from a list with bootstrap estimates of transition probabilities into multiple states. This function is not meant to be called by the user.

### Usage

```
extract_function(list_object, tstate)
```

### Arguments

list\_object A list in which each individual element is a single bootstrap estimate of the

probability of transition into different states.

tstate The state whose bootstrap estimates of transition probabilities we wish to extract

from list\_object.

#### **Details**

This function is an ancillary function of CIs\_for\_target\_state, which in turn is an ancillary function of boot\_ebmstate.

### Value

Bootstrap estimates of transition probabilities into target state 'tstate'.

### Author(s)

Rui Costa

### See Also

```
CIs_for_target_state; boot_ebmstate
```

joint\_cum\_hazard\_function

Compute the cumulative hazard of leaving a given state

### **Description**

This function is not meant to be called by the user. It is an internal function of probtrans\_by\_convolution\_clockforward and probtrans\_by\_convolution\_clockreset.

joint\_cum\_hazard\_function returns the cumulative hazard of leaving state i to any state that can be reached directly from i, at each of the time points in t. There is no explicit argument i: this state is entirely defined by the transitions that can occur when the patient is in it (and these transitions are given in the argument competing\_transitions).

### Usage

```
joint_cum_hazard_function(t, competing_transitions, spline_list)
```

#### **Arguments**

t A vector of time points.

competing\_transitions

The transitions that can occur when the process is in state i.

spline\_list

A list whose elements are spline functions approximating the cumulative hazard of making each possible transition in the process. This is normally a list object created by running cumhaz\_splines.

#### Value

A vector with the cumulative hazard of leaving a given state evaluated at given time points.

### Author(s)

Rui Costa

#### See Also

probtrans\_by\_convolution\_clockforward; probtrans\_by\_convolution\_clockreset; cumhaz\_splines.

loo\_ebmstate 15

| loo_ebmstate | Leave-one-out estimation |  |
|--------------|--------------------------|--|

### Description

This function computes leave-one-out estimation of regression coefficients, cumulative hazard functions, and transition probability functions.

### Usage

```
loo_ebmstate(
   mstate_data,
   mstate_data_expanded,
   which_group,
   patient_IDs,
   initial_state,
   tmat,
   time_model,
   backup_file = NULL,
   input_file = NULL,
   coxrfx_args = list(),
   msfit_args = NULL,
   probtrans_args = NULL)
```

### Arguments

| mstate_data          | Data in 'long format'.  |  |  |
|----------------------|---|--|--|
| mstate_data_expanded |   |  |  |
|                      | Data in 'long format', possibly with 'expanded' covariates (as obtained by running mstate::expand.covs).  |  |  |
| which_group          | A character vector with the same meaning as the 'groups' argument of the function CoxRFX but named (with the covariate names).  |  |  |
| patient_IDs          | The IDs of the patients whose cumulative hazards and transition probabilities one wishes to estimate.   |  |  |
| initial_state        | The initial state for which transition probability estimates should be computed   |  |  |
| tmat                 | Transition matrix for the multi-state model, as obtained by running mstate::transMat  |  |  |
| time_model           | The model of time-dependency: either 'clockforward' or 'clockreset'.  |  |  |
| backup_file          | Path to file. Objects generated while the present function is running are stored in this file. This avoids losing all estimates if and when the algorithm breaks down. See argument input_file. |  |  |
| input_file           | Path to backup_file (see argument backup_file). If this argument is given, all other arguments should be NULL.  |  |  |
| coxrfx_args          | Named list with arguments to the CoxRFX function other than Z, surv and groups.   |  |  |
|                      |   |  |  |

16 MakeInteger

 ${\tt msfit\_args} \qquad \qquad {\tt Named \ list \ with \ arguments \ to \ the \ msfit\_generic.coxrfx \ function \ other \ than}$ 

object, newdata and trans.

 $probtrans\_args \quad Named \ list \ with \ arguments \ to \ the \ probtrans\_ebm state \ function \ other \ than$ 

initia\_state,cumhaz and model.

#### Details

In a given bootstrap sample there might not be enough information to generate estimates for all coefficients. If a covariate has little or no variation in a given bootstrap sample, no estimate of its coefficient will be computed. The present function will keep taking bootstrap samples until every coefficient has been estimated at least min\_nr\_samples times.

#### Value

A list with: 95% bootstrap intervals for each regression coefficient and for transition probabilities; bootstrap samples of regression coefficients, cumulative hazards and transition probabilities.

### Author(s)

Rui Costa

MakeInteger

Convert factor to integer.

### **Description**

Convert factor to integer.

### Usage

MakeInteger(v)

### **Arguments**

٧

A factor vector.

#### Details

An internal function of CoxRFX, not meant to called directly by the user.

### Value

A data frame with columns corresponding to levels in the factor.

### Author(s)

Moritz Gerstung

msfit\_generic 17

### See Also

CoxRFX

msfit\_generic

Compute subject-specific transition hazards.

### Description

This function computes subject-specific or overall cumulative transition hazards for each of the possible transitions in the multi-state model. This help page is an adaptation of the mstate::msfit help page.

### Usage

```
msfit_generic(object, ...)
## Default S3 method:
msfit_generic(
  object,
  newdata,
  variance = TRUE,
  vartype = c("aalen", "greenwood"),
  trans,
  ...
)
## S3 method for class 'coxrfx'
msfit_generic(object, newdata, trans, ...)
```

#### **Arguments**

object An object describing the fit of a multi-state Cox model.

... Further arguments

newdata A data frame in 'long format'. See details.

variance A logical value indicating whether the (co-)variances of the subject-specific tran-

sition hazards should be computed.

vartype A character string specifying the type of variances to be computed (so only

needed if variance=TRUE).

trans Transition matrix describing the states and transitions in the multi-state model.

See trans in msprep for more detailed information.

18 msfit\_generic

#### **Details**

The purpose of msfit\_generic is to be able to use mstate::msfit on model fit objects of class coxrfx (i.e. objects generated by CoxRFX). This can now be done with msfit\_generic.coxrfx, which introduces minor modifications to mstate::msfit. In particular, it precludes msfit from computing the (co-)variances of transition hazard estimators, as this computation relies on asymptotic results for the fixed effects Cox model (see de Wreede et al, 2010, section 2.3.2). The method msfit\_generic.default corresponds to the original mstate::msfit function. The data frame given as newdata input needs to have one row for each transition in the multi-state model, and one column for each covariate. An additional column strata (numeric) is needed to describe for each transition to which stratum it belongs. The name has to be strata, even if in the original coxph call another variable was used. See msfit for more details.

### Value

An 'msfit' object. See msfit for details. If the S3 method msfit\_generic.coxrfx is called, the returned object will be of class c(msfit,coxrfx); otherwise, it will be of class msfit.

#### Author(s)

Rui Costa, adapting the work of L. de Wreede, M. Fiocco and H. Putter in the mstate package.

#### References

de Wreede LC, Fiocco M, and Putter H (2010). The mstate package for estimation and prediction in non- and semi-parametric multi-state and competing risks models. *Computer Methods and Programs in Biomedicine* **99**, 261–274.

#### See Also

```
msfit; msprep; plot.msfit.
```

### **Examples**

```
# Compute cumulative hazard rates
# under a (pre-estimated) empirical Bayes Cox
# model.

#load simulated data (illness-death model,
#500 patients) and estimated empirical
# Bayes Cox model
data("mstate_data_sample")
data("coxrfx_object_sample")

# Make objects 'surv' and 'Z'
# with the data used in the estimation

#outcome data
surv<-coxrfx_object_sample$surv

#covariate data</pre>
```

msfit\_object\_sample 19

```
Z<-coxrfx_object_sample$Z
 # Build a data frame 'patient_data'
 # with the covariate values for which
 # cumulative hazards are to be computed
 # (patient 1 covariate values in this case).
  # 'patient_data' must have one row for each
 # transition in the model
 # and the same columns as 'Z'. The assignment
 # of transitions to strata (made in the 'strata'
  # column) must follow the original model in
 # 'coxrfx_object_sample'.
 patient_data<-mstate_data_sample[mstate_data_sample$id==1,</pre>
     ,drop=FALSE][rep(1,3),]
 patient_data$strata<-patient_data$trans<-1:3</pre>
 patient_data<-mstate::expand.covs(patient_data,</pre>
     covs=names(patient_data)[!names(patient_data)%in%
    c("id", "from", "to", "trans", "Tstart", "Tstop", "time",
     "to", "trans", "Tstart", "Tstop", "time", "status",
     "strata")],append=TRUE)
  # compute cumulative hazards
 msfit_object<-msfit_generic(coxrfx_object_sample,</pre>
                               patient_data,
                               coxrfx_object_sample$tmat)
  # show estimates
 print(msfit_object)
msfit_object_sample
                          Estimated cumulative hazard rates under an empirical Bayes Cox
```

### Description

An RData object containing estimated cumulative hazards, obtained by running msfit\_generic on the object\_coxrfx\_object\_sample (also included in the present package).

model (example)

### Usage

```
msfit_object_sample
```

#### **Format**

An object of class c(msfit,coxrfx). See msfit\_generic and mstate::msfit for details.

#### See Also

```
coxrfx_object_sample.
```

20 mstate\_data\_sample

mstate\_data

An example of long-format multistate data

### Description

An RData object containing disease progression data for a sample of 576 patients with myelodys-plastic syndromes (MDS), as an example of long-format multistate data.

#### Usage

mstate\_data

#### **Format**

A data frame.

mstate\_data\_sample

A simulated event-history data set

### Description

A data set generated by simulation from an illness-death Cox model. This is an object of double class 'data.frame' and 'msdata', whose 'trans' attribute is a transition matrix (attr(mstate\_data\_sample, "trans")).

### Usage

mstate\_data\_sample

#### **Format**

A data frame with 649 rows and 18 variables (250 patients):

id patient identification number

from state in which the patient is

to state to which the patient is at risk of going to

trans transition ID number

Tstart when the risk of the transition started

**Tstop** the time at which the risk of the transition ended or the last follow-up time (whichever happened first)

time Tstop-Tstart

status did the transition occur at Tstop?

Cov1,Cov2,Cov3,Cov4,Cov5,Cov6,Cov7,Cov8,Cov9,Cov10 covariates

print.coxrfx 21

print.coxrfx

Print method for CoxRFX objects

### **Description**

This function implicitly calls summary.coxrfx().

### Usage

```
## S3 method for class 'coxrfx'
print(x, ...)
```

### Arguments

x A coxrfx object

... further arguments passed to or from other methods.

#### **Details**

Prints two data frames, one with hyperparameter estimates and another with regression coefficient estimates.

#### Value

Returns an invisible NULL object.

#### Author(s)

Moritz Gerstung & Rui Costa

print.msfit

Print method for msfit objects generated by msfit\_generic

### **Description**

This method is a simple call to print.default. Its main purpose is to override print.coxrfx when printing an object of double class msfit and coxrfx.

### Usage

```
## S3 method for class 'msfit' print(x, ...)
```

### **Arguments**

x An object of class msfit or double class msfit and coxrfx.

. . . Further arguments passed to or from other methods.

#### Value

The input object (an object of double class msfit and coxrfx).

#### Author(s)

Rui Costa

probtrans\_by\_convolution

Compute all transition probabilities from a given state using convolu-

### Description

probtrans\_by\_convolution is an internal function of probtrans\_ebmstate and is not meant to be called directly by the user. It is itself a wrapper for the functions probtrans\_by\_convolution\_clockforward and probtrans\_by\_convolution\_clockreset, which are the workhorses of the convolution algorithm.

#### Usage

```
probtrans_by_convolution(tmat, cumhaz, from_state, model, max_time, nr_steps)
```

### **Arguments**

tmat A transition matrix extracted from the cumhaz argument to probtrans\_ebmstate.

cumhaz msfit object (argument passed on from probtrans\_ebmstate).
from\_state Initial state (argument passed on from probtrans\_ebmstate).

max\_time The maximum time for which transition probabilities are estimated.

nr\_steps The number of steps in the convolution algorithm (larger increases precision but

makes it slower)

#### **Details**

For more information on the arguments of this function see probtrans\_ebmstate.

### Author(s)

Rui Costa & Moritz Gerstung

#### See Also

probtrans\_ebmstate;probtrans\_by\_convolution\_clockforward; probtrans\_by\_convolution\_clockreset.

```
probtrans_by_convolution_clockforward
```

Compute transition probabilities under a clock-forward model using a convolution algorithm.

#### **Description**

Compute transition probabilities for a given starting state and target state under a clock-forward model, using a convolution algorithm.

probtrans\_by\_convolution\_clockforward is an internal function of probtrans\_by\_convolution and is not meant to be called directly by the user.

#### Usage

```
probtrans_by_convolution_clockforward(
   tmat,
   cumhaz,
   from_state,
   to_state,
   spline_list,
   unique_paths_object,
   time
)
```

### Arguments

tmat Transition matrix.

cumhaz msfit object.

from\_state Initial state.

to\_state Target state.

A list whose elements are spline functions approximating the cumulative hazard

of making each possible transition in the process. This is normally a list object

created by running  $cumhaz\_splines$ .

unique\_paths\_object

spline\_list

An object created by running unique\_paths.

time A vector of ordered time points.

#### Author(s)

Rui Costa & Moritz Gerstung

#### See Also

probtrans\_ebmstate; probtrans\_by\_convolution\_clockreset; probtrans\_by\_convolution; unique\_paths; cumhaz\_splines. probtrans\_by\_convolution\_clockreset

Compute transition probabilities under a clock-reset model using a convolution algorithm.

#### **Description**

Compute transition probabilities for a given starting state and target state under a clock-reset model with a single time scale (sojourn time), using a convolution algorithm.

probtrans\_by\_convolution\_clockreset is an internal function of probtrans\_by\_convolution and is not meant to be called directly by the user.

#### Usage

```
probtrans_by_convolution_clockreset(
   tmat,
   cumhaz,
   from_state,
   to_state,
   spline_list,
   unique_paths_object,
   time
)
```

### Arguments

tmat Transition matrix.
cumhaz msfit object.
from\_state Initial state.
to\_state Target state.

spline\_list A list whose elements are spline functions approximating the cumulative hazard

of making each possible transition in the process. This is normally a list object

created by running cumhaz\_splines.

unique\_paths\_object

An object created by running unique\_paths.

time A vector of ordered time points.

#### Author(s)

Rui Costa & Moritz Gerstung

#### See Also

probtrans\_ebmstate; probtrans\_by\_convolution\_clockforward; probtrans\_by\_convolution; unique\_paths; cumhaz\_splines. probtrans\_ebmstate 25

probtrans\_ebmstate

Compute subject-specific transition probabilities using convolution.

### **Description**

Compute subject-specific transition probabilities using convolution.

### Usage

```
probtrans_ebmstate(
   initial_state,
   cumhaz,
   model,
   max_time = NULL,
   nr_steps = 10000
)
```

### **Arguments**

initial\_state The present function estimates transition probabilities from the state given in

this argument.

cumhaz An msfit object created by running mstate or mstate\_generic.

model Either 'clockforward' or 'clockreset'. See details.

max\_time The maximum time for which transition probabilities are estimated.

nr\_steps The number of steps in the convolution algorithm (larger increases precision but

makes it slower)

#### **Details**

The clock-forward model is a model in which the transition hazard rates depend only on time since the initiating event. The clock-reset model has a single time scale: the sojourn time in the current state.

The algorithm behind probtrans\_ebmstate is based on the convolution of density and survival functions and is suitable for processes with a tree-like transition structure only.

#### Value

An object of class 'probtrans'. See the 'value' section in the help page of mstate::probtrans.

#### Author(s)

Rui Costa & Moritz Gerstung

### See Also

```
probtrans;
```

26 probtrans\_fft

### **Examples**

probtrans\_fft

Compute subject-specific transition probabilities using a convolution algorithm based on the Fast Fourier transform.

#### **Description**

Compute subject-specific transition probabilities using a convolution algorithm based on the Fast Fourier transform.

#### Usage

```
probtrans_fft(initial_state, cumhaz, max_time, nr_steps = 10000)
```

### Arguments

initial\_state The present function estimates state occupation probabilities from the state given

in this argument.

cumhaz An msfit object created by running mstate or mstate\_generic.

max\_time The maximum time for which transition probabilities are estimated.

nr\_steps The number of steps in the convolution algorithm (larger increases precision but

makes it slower)

### Details

The time argument is crucial for precision. The density of time points and the upper time limit should be increased until the estimated curves become stable. A useful rule of thumb is to set the upper time limit to a time point in which the probability of each transient state is zero and the probability of each absorbing state is constant.

For the same approximation grid, probtrans\_fft doesn't always yield the same result as probtrans\_ebmstate (semi-Markov version), even though they are meant to approximate exactly the same convolution. probtrans\_ebmstate is sensitive to the grid interval size, but not such much to the maximum grid time. probtrans\_fft is sensitive to both these parameters, as referred above.

The algorithm behind probtrans\_ebmstate is based on the convolution of density and survival functions and is suitable for processes with a tree-like transition structure only.

probtrans\_mstate 27

#### Value

An object of class 'probtrans'. See the 'value' section in the help page of mstate::probtrans.

#### Author(s)

Rui Costa

#### See Also

```
probtrans; probtrans_ebmstate
```

probtrans\_mstate

Compute subject-specific or overall transition probabilities

### **Description**

This function is a wrapper for mstate::probtrans. Its purpose is to preclude the computation of (co-)variances of the transition probability estimator when the fitted Cox model is empirical Bayes. This help page is an adaptation of the mstate::probtrans help page.

### Usage

```
probtrans_mstate(object, ...)

## Default S3 method:
probtrans_mstate(
   object,
   predt,
   direction = c("forward", "fixedhorizon"),
   method = c("aalen", "greenwood"),
   variance = TRUE,
   covariance = FALSE,
   ...
)

## S3 method for class 'coxrfx'
probtrans_mstate(object, predt, direction = c("forward", "fixedhorizon"), ...)
```

### Arguments

object An msfit object containing estimated cumulative hazards for each of the transi-

tions in the multi-state model and, if standard errors are requested, (co)variances

of these cumulative hazards for each pair of transitions.

... other arguments.

predt A positive number indicating the prediction time. This is either the time at

which the prediction is made (if direction= "forward") or the time for which the

prediction is to be made (if direction="fixedhorizon").

28 probtrans\_mstate

direction

One of "forward" (default) or "fixedhorizon", indicating whether prediction is forward or for a fixed horizon.

Method

A character string specifying the type of variances to be computed (so only needed if either variance or covariance is TRUE). Possible values are "aalen" or "greenwood".

Variance

Logical value indicating whether standard errors are to be calculated (default is TRUE).

Covariance

Logical value indicating whether covariances of transition probabilities for different states are to be calculated (default is FALSE).

#### **Details**

probtrans\_mstate computes estimates of transition probabilities for an object generated by msfit\_generic. It calls the method probtrans\_mstate.coxrfx, if the msfit object was generated by msfit\_generic.coxrfx, or the method probtrans\_mstate.default otherwise. Both methods are identical to the function mstate::probtrans. The only reserve is that probtrans\_mstate.coxrfx does not allow the computation of the (co-)variances of the transition probability estimator. In fact, this computation relies on asymptotic results for the *fixed* effects Cox model (see de Wreede et al, 2010, section 2.3.2), and msfit\_generic.coxrfx produces estimates of cumulative hazards under a random effects/empirical Bayes Cox model.

probtrans\_mstate should only be used for Markov models, as it relies on product limit calculations.

#### Value

An object of class probtrans. See the 'value' section in the help page of probtrans for details.

#### Author(s)

Rui Costa, adapting the work of L. de Wreede, M. Fiocco and H. Putter in the mstate package.

#### References

de Wreede LC, Fiocco M, and Putter H (2010). The mstate package for estimation and prediction in non- and semi-parametric multi-state and competing risks models. *Computer Methods and Programs in Biomedicine* **99**, 261–274.

#### See Also

probtrans; msfit; msfit\_generic.

successful\_transitions 29

successful\_transitions

Find the unique possible path until an absorbing state

### Description

From a unique\_paths object that shows all possible paths until absorption from an initial state, successful\_transitions picks the path that finishes in to\_state, if there is one. The initial state is the one defined in the argument from\_state to the function unique\_paths. The process must have a tree-like structure.

### Usage

```
successful_transitions(unique_paths_object, to_state, tmat)
```

### **Arguments**

unique\_paths\_object

An object created by running unique\_paths.

to\_state An absorbing state.

tmat Transition matrix.

#### **Details**

This function is used by probtrans\_by\_convolution\_clockforward and probtrans\_by\_convolution\_clockreset. It is not meant to be called by the user.

### Value

A vector with the unique sequence of states between two states.

### Author(s)

Rui Costa

#### See Also

unique\_paths; probtrans\_by\_convolution\_clockforward; probtrans\_by\_convolution\_clockreset.

30 unique\_paths

summary.coxrfx

A summary method for CoxRFX models

### Description

This function prints the point estimates of parameters and hyperparameters contained in a coxrfx object.

### Usage

```
## S3 method for class 'coxrfx'
summary(object, ...)
```

### **Arguments**

object

A coxrfx object (obtained by running the function CoxRFX).

. . .

Further arguments passed to or from other methods.

#### **Details**

Prints two data frames, one with hyperparameter estimates and another with regression coefficient estimates.

### Value

Returns an invisible NULL object.

### Author(s)

Rui Costa

unique\_paths

Find all possible paths until absorption from a given starting state

### **Description**

unique\_paths finds all possible sequences of states until absorption when the process has a tree-like structure.

### Usage

```
unique_paths(from_state, tmat)
```

unique\_paths 31

### **Arguments**

from\_state Initial state.

tmat A transition matrix describing the states and transitions in the multi-state model,

as can be obtained by running transMat. See argument trans in msprep (mstate

package) for more detailed information.

#### **Details**

This function is used by the function probtrans\_by\_convolution. It is not meant to be called by the user.

### Value

A matrix where each column is a sequence of states taken by the process until absorption. There are as many columns as the number of possible paths until absorption.

### Author(s)

Rui Costa

### See Also

probtrans\_by\_convolution; transMat.

## **Index**

```
* datasets
    coxrfx_object_sample, 11
    msfit_object_sample, 19
    mstate_data, 20
    mstate_data_sample, 20
* package
    ebmstate-package, 2
boot_coxrfx, 3, 6
boot_ebmstate, 4, 7, 12, 13
boot_probtrans, 5
CIs_for_target_state, 6, 13
convolute_clockforward, 7
convolute_clockreset, 8
CoxRFX, 8, 11, 17, 18
coxrfx_object_sample, 11, 19
cumhaz_splines, 12, 14, 23, 24
cumhazCIs\_for\_target\_transition, 11
ebmstate-package, 2
expand.covs, 6
extract_function, 7, 13
joint_cum_hazard_function, 14
loo_ebmstate, 15
MakeInteger, 16
msfit, 12, 13, 18, 28
msfit_generic, 12, 13, 17, 19, 28
msfit_object_sample, 19
msprep, 17, 18, 31
mstate::msfit, 19
mstate_data, 20
mstate_data_sample, 11, 20
plot.msfit, 18
print.coxrfx, 21
print.msfit, 21
probtrans, 25, 27, 28
```

```
probtrans_by_convolution, 13, 22, 23, 24,
probtrans_by_convolution_clockforward,
         7, 14, 22, 23, 24, 29
probtrans_by_convolution_clockreset, 8,
        14, 22, 23, 24, 29
probtrans_ebmstate, 6, 22-24, 25, 27
probtrans_fft, 26
probtrans_mstate, 27
successful_transitions, 29
summary.coxrfx, 30
survival::coxph.object, 9, 10
survival::Surv, 10
transMat, 6, 31
unique_paths, 23, 24, 29, 30
```