

Package: dnn (via r-universe)

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Author Bingshu E. Chen [aut, cre], Patrick Norman [aut, ctb], Wenyu Jiang [ctb], Wanlu Li [ctb]

Maintainer Bingshu E. Chen <bingshu.chen@queensu.ca>

Depends R (>= 3.5.0), ggplot2, survival, Rcpp

Imports methods

LinkingTo Rcpp, RcppArmadillo

Description Contains tools to build deep neural network with flexible users define loss function and probability models. Several applications included in this package are, 1) The (deepAFT) model, a deep neural network model for accelerated failure time (AFT) model for survival data. 2) The (deepGLM) model, a deep neural network model for generalized linear model (glm) for continuous, categorical and Poisson data.

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Contents

dnn-package	2
activation	3
bwdNN	5
deepAFT	6
deepGLM	9
deepSurv	11

dnnControl	13
dnnFit	14
dNNmodel	16
fwdNN	17
hyperTuning	18
ibs	20
msePICW	21
optimizerSGD	22
plot	23
predict	24
print	25
residuals	26
rsurv	27
survfit	28
Index	30

dnn-package	<i>An R package for the deep neural networks probability and statistics models</i>
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Description

This package provides tools for deep neural network which allow user define loss function for complex outcome data with probability and statistics models such as generalized linear models, accelerated failure time (AFT) models, and Cox proportional hazards models.

It contains the essential building blocks such as feed forward network and back propagation. This gives users the flexibility to write their own loss function (i.e. cost function) and train the neural network.

Details

{dnn} is a R package for deep learning neural network with probability models that use the negative of the log-likelihood as the loss function. It provides functions for feed forward network from covariates to the output layer and back propagation to find the derivatives of the weight parameters. Different optimization methods such as stochastic gradient descent (SGD), Momentum and ADAM can be used to train the network.

Currently, {dnn} can be install by

the package source file 'dnn.tar.gz', use

```
install.packages("dnn.tar.gz", repos = NULL, type = "source")
```

users can use the following steps to install the most recent version of 'dnn' package:

1. First, you need to install the 'devtools' package. You can skip this step if you have 'devtools' installed in your R. Invoke R and then type

```
install.packages("devtools")
```

2. Load the devtools package.

```
library(devtools)
```

3. Install "dnn" package from github with R command

```
install_github("statapps/dnn")
```

A stable version of View the "dnn" package is also available from the Comprehensive R Archive Network (<https://CRAN.R-project.org/package=dnn>) and can be installed using R command

```
install.packages("dnn")
```

Author(s)

Bingshu E. Chen

Maintainer: Bingshu E. Chen <bingshu.chen@queensu.ca>

See Also

[dNNmodel](#), [bwdNN](#), [fwdNN](#), [deepAFT](#), [deepGLM](#), [deepSurv](#), [coxph](#), [glm survival](#)

Examples

```
# Create the models with 3 layers
model = dNNmodel(units=c(8, 6, 1), activation = c('elu', 'relu', 'sigmoid'),
  input_shape = c(3))
print(model)
#
# Feed forward network with dummy data x
x = matrix(runif(15), nrow = 5, ncol = 3)
cache = fwdNN(x, model)
#
# Back propagation with dummy dy = dL/dyhat and minin batch for SGD
dy = as.matrix(runif(5, -0.1, 0.1), nrow = 5)
dW = bwdNN(dy, cache, model)
#
# Gradient descent with SGD
lr_rate = 0.0001
sgd = function(w, dw) {w-lr_rate*dw}
model$params = mapply(sgd, w = model$params, dw = dW)
```

activation

Activation function

Description

Different type of activation functions and the corresponding derivatives

Usage

```

sigmoid(x)
elu(x)
relu(x)
lrelu(x)
idu(x)
dsigmoid(y)
delu(y)
drelu(y)
dlrelu(y)
dtanh(y) #activation function tanh(x) is already available in R

```

Arguments

x	input of the activation function
y	input of the derivative of the activation function

Details

Each function returns either the activation function (e.g. sigmoid, relu) or its derivative (e.g. dsigmoid, drelu).

Value

An activation function is applied to x and returns a matrix the same size as x. The detail formula for each activation function is:

sigmoid	return $1/(1+\exp(-x))$
elu	return x for $x>0$ and $\exp(x)-1$ for $x<0$
relu	return x for $x>0$ and 0 for $x<0$
lrelu	return x for $x>0$ and $0.1*x$ for $x<0$
tanh	return $\tanh(x)$
idu	return (x)

Author(s)

Bingshu E. Chen

See Also

[bwdNN](#), [fwdNN](#), [dNNmodel](#), [optimizerSGD](#), [optimizerNAG](#)

Examples

```

# Specify a dnn model with user define activation function in layer 2.
softmax = function(x) {log(1+exp(x))} # y = log(1+exp(x))
dsoftmax = function(y) {sigmoid(y)} # x = exp(y)/(1+exp(y))
model = dNNmodel(units=c(8, 6, 1), activation= c('relu', 'softmax', 'sigmoid'),

```

```

        input_shape = c(3))
print(model)

```

bwdNN

*Back propagation for dnn Models***Description**

{bwdNN} is an R function for back propagation in DNN network.

Usage

```

#
# To apply back propagation in with a feed forward model
#
# use
#
  bwdNN(dy, cache, model)
#
# to calculate derivative of dL/dW

```

Arguments

dy	the derivative of the cost function with respect to the output layer of the fwdNN function.
cache	the cached output of fwdNN.
model	a model return from dNNmodel function.

Details

Here 'dy' plays an import role in the back propagation { bwdNN } since the probability model's loss function takes the output layer of the { dnn } (denote as yhat) as one of its parameter. Then 'dy' equals to the partial derivative of the loss function (-Log Likelihood) with respect to yhat, that is, $dy = dL/d(yhat)$. For example, if the 'dnn' predicts the probability ($yhat = p$) for the mixture of two populations $f1$ and $f2$, then the likelihood function is $f = p*f1 + (1-p)*f2$, and the loss function is $L = -\log(p*f1+(1-p)*f2)$. Hence, $dy = dL/dp = -(f1-f2)/f$.

'cache' is the cache of each input layer generated from the { fwdNN } function.

The function { bwdCheck } calculates the numerical derivatives of dL/dW , which can be used to check if the back propagation is correct or not, see example below.

Value

A list contains the derivatives of weight parameter W is returned.

Author(s)

Bingshu E. Chen (bingshu.chen@queensu.ca)

See Also

[dNNmodel](#), [fwdNN](#), [plot.dNNmodel](#), [print.dNNmodel](#), [summary.dNNmodel](#),

Examples

```
### define a dnn model, calculate the feed forward network
model = dNNmodel(units = c(8, 6, 1),
                 activation = c("elu", "sigmoid", "sigmoid"), input_shape = 3)
print(model)
x = matrix(runif(15), nrow = 5, ncol = 3)
cache = fwdNN(x, model)
# dy = dL/dp, where L is the cost function such as the
# log-likelihood and p is the output layer parameter of the DNN
dy = as.matrix(runif(5, -0.1, 0.1), nrow = 5) # a dummy dy for bwdNN input
y = predict(model, x) + dy

# back propagation
dW = bwdNN(dy, cache, model)
dw = bwdCheck(x, y, model)
print(dw[[1]])
print(dw[[1]])
```

deepAFT

Deep learning for the accelerated failure time (AFT) model

Description

Fit a deep learning survival regression model. These are location-scale models for an arbitrary transform of the time variable; the most common cases use a log transformation, leading to accelerated failure time models.

Usage

```
deepAFT(x, ...)

## S3 method for class 'formula'
deepAFT(formula, model, data, control = list(...), method =
        c("BuckleyJames", "ipcw", "transform"), ...)

## Default S3 method:
deepAFT(x, y, model, control, ...)

## S3 method for class 'ipcw'
deepAFT(x, y, model, control, ...)
# use:
# deepAFT.ipcw(x, y, model, control)
# or
# class(x) = "ipcw"
```

```
# deepAFT(x, y, model, control)
#
## S3 method for class 'trans'
deepAFT(x, y, model, control, ...)
# use:
# class(x) = "transform"
# deepAFT(x, y, model, control)
```

Arguments

formula	a formula expression as for other regression models. The response is usually a survival object as returned by the 'Surv' function. See the documentation for 'Surv', 'lm' and 'formula' for details.
model	deep neural network model, see below for details.
data	a data.frame in which to interpret the variables named in the formula.
x	Covariates for the AFT model
y	Surv object for the AFT model
method	methods to handle censoring data in deep AFT model fit, 'BuckleyJames' for Buckley and James method, 'ipcw' for inverse probability censoring weights method. 'transform' for transformation based on book of Fan and Gijbels (1996, page 168)
control	a list of control values, in the format produced by 'dnnControl'. The default value 'dnnControl()'
...	optional arguments

Details

See "Deep learning with R" for details on how to build a deep learning model.

The following parameters in 'dnnControl' will be used to control the model fit process.

'epochs': number of deep learning epochs, default is 100.

'batch_size': batch size, default is 128. 'NaN' may be generated if batch size is too small and there is not event in a batch.

'verbose': verbose = 1 for print out verbose during the model fit, 0 for not print.

'epsilon': epsilon for convergence check, default is epsilon = 0.001.

'max.iter': number of maximum iteration, default is max.iter = 100.

'censor.groups': a vector for censoring groups. A KM curve for censoring will be fit for each group. If a matrix is provided, then a Cox model will be used to predict the censoring probability.

When the variance for covariance matrix X is too large, please use `xbar = apply(x, 2, stdx)` to standardize X.

Value

An object of class "deepAFT" is returned. The deepAFT object contains the following list components:

x	Covariates for the AFT model
y	Survival object for the AFT model, $y = \text{Surv}(\text{time}, \text{event})$
model	A fitted artificial neural network (ANN) model
mean.ipt	mean survival or censoring time
predictor	predictor score $\mu = f(x)$
risk	risk score = $\exp(\text{predictor})$
method	method for deepAFT fitting, either Buckley-James, IPCW or transformed model

Note

For right censored survival time only

Author(s)

Chen, B. E. and Norman P.

References

Buckley, J. and James, I. (1979). Linear regression with censored data. *Biometrika*, 66, page 429-436.

Norman, P. Li, W., Jiang, W. and Chen, B. E. (2024). DeepAFT: A nonparametric accelerated failure time model with artificial neural network. Manuscript submitted to *Statistics in Medicine*.

Chollet, F. and Allaire J. J. (2017). *Deep learning with R*. Manning.

See Also

[print.deepAFT](#), [survreg](#), [ibs.deepAFT](#)

Examples

```
## Example for deep learning model for AFT survival data
set.seed(101)
### define model layers
model = dnnmodel(units = c(4, 3, 1), activation = c("elu", "sigmoid", "sigmoid"),
                 input_shape = 3)
x = matrix(runif(15), nrow = 5, ncol = 3)
time = exp(x[, 1])
status = c(1, 0, 1, 1, 1)
fit = deepAFT(Surv(time, status) ~ x, model)
```


Description

Fit generalized linear models (Gaussian, Binomial and Poisson) using deep learning neural network (DNN). The glm formula is specified by giving a symbolic description of the predictor and a description of the error distribution.

Usage

```
deepGlm(formula, model, family = c("gaussian", "binomial",
    "poisson"), data, epochs = 200, lr_rate = 1e-04,
    batch_size = 64, alpha = 0.7, lambda = 1, verbose = 0,
    weights = NULL, ...)
```

Arguments

formula	a formula expression as for other regression models. The response is usually an object for glm response variable. See the documentation for 'glm', 'lm' and 'formula' for details.
model	a deep neural network model, created by function dNNmodel().
family	a description of the error distribution and link function to be used in the model. This can be either a character string of 'gaussian', 'binomial', or 'poisson', naming a family function, or result of a call to a family function (See 'family' for details of family functions.)
data	a data.frame in which to interpret the variables named in the formula.
epochs	number of deep learning epochs, default is 200.
batch_size	batch size, default is 64. 'NaN' may be generated if batch size is too small and there is not event in a batch.
lr_rate	learning rate for the gradient descent algorithm, default is lr_rate = 1e-04.
weights	an optional vector of 'prior weights' to be used in the fitting process. Should be NULL or a numeric vector.
alpha	momentum rate for the gradient descent method, alpha takes value in [0, 1), default is alpha = 0.70.
lambda	L2 regularization parameter for deep learning.
verbose	verbose = 1 for print out verbose during the model fit, 0 for not print.
...	optional arguments

Details

See [dNNmodel](#) for details on how to specify a deep learning model.

The following parameters in 'dnnControl' will be used to control the model fit process.

'epochs': number of deep learning epochs, default is 30.

'verbose': verbose = 1 for print out verbose during the model fit, 0 for not print.

When the variance for covariance matrix X is too large, please use `xbar = scale(x)` to standardize X .

Value

An object of class "deepGlm" is returned. The deepGlm object contains the following list components:

x	Covariates for glm model
y	Object for glm model
model	dnn model
predictor	predictor score $\mu = f(x)$
risk	risk score = $\exp(\text{predictor})$

Note

For glm models with Gaussian, Binomial and Poisson only

Author(s)

Chen, B. E.

References

Chollet, F. and Allaire J. J. (2017). Deep learning with R. Manning.

See Also

[deepAFT](#), [dNNmodel](#), [predict.deepGlm](#), [print.deepSurv](#), [glm](#)

Examples

```
## Example for deep learning for glm models
set.seed(101)
### define model layers
model = dNNmodel(units = c(4, 3, 1), activation = c("elu", "sigmoid", "sigmoid"),
                 input_shape = 3)
x = matrix(runif(15), nrow = 5, ncol = 3)
y = exp(x[, 1] + rnorm(5))

fit = deepGlm(y ~ x, model, family = "gaussian")
```

 deepSurv

Deep learning for the Cox proportional hazards model

Description

Fit a survival regression model under the Cox proportional hazards assumption using deep learning neural network (DNN).

Usage

```
deepSurv(formula, model, data, epochs = 200, lr_rate = 1e-04,
         batch_size = 64, alpha = 0.7, lambda = 1, verbose = 0,
         weights = NULL, ...)
```

Arguments

formula	a formula expression as for other regression models. The response is usually a survival object as returned by the 'Surv' function. See the documentation for 'Surv', 'lm' and 'formula' for details.
model	a deep neural network model, created by function dNNmodel().
data	a data.frame in which to interpret the variables named in the formula.
epochs	number of deep learning epochs, default is 200.
batch_size	batch size, default is 64. 'NaN' may be generated if batch size is too small and there is not event in a batch.
lr_rate	learning rate for the gradient descent algorithm, default is lr_rate = 1e-04.
weights	an optional vector of 'prior weights' to be used in the fitting process. Should be NULL or a numeric vector.
alpha	momentum rate for the gradient descent method, alpha takes value in [0, 1), default is alpha = 0.70.
lambda	L2 regularization parameter for deep learning.
verbose	verbose = 1 for print out verbose during the model fit, 0 for not print.
...	optional arguments

Details

See "Deep learning with R" for details on how to build a deep learning model.

The following parameters in 'dnnControl' will be used to control the model fit process.

'epochs': number of deep learning epochs, default is 30.

'verbose': verbose = 1 for print out verbose during the model fit, 0 for not print.

'epsilon': epsilon for convergence check, default is epsilon = 0.001.

'max.iter': number of maximum iteration, default is max.iter = 30.

When the variance for covariance matrix X is too large, please use `xbar = scale(x)` to standardize X.

Value

An object of class "deepSurv" is returned. The deepSurv object contains the following list components:

x	Covariates for Cox model
y	Surv object for Cox model
model	dnn model
predictor	predictor score $\mu = f(x)$
risk	risk score = $\exp(\text{predictor})$

Note

For right censored survival time only

Author(s)

Chen, B. E. wrote the R code using the partial likelihood cost function proposed by Katzman et al (2018).

References

Katzman JL, Shaham U, Cloninger A, Bates J, Jiang T, Kluger Y. DeepSurv: Personalized treatment recommender system using a Cox proportional hazards deep neural network. BMC Medical Research Methodology 2018; 18: 24.

See Also

[deepAFT](#), [deepGlm](#), [print.deepSurv](#), [survreg](#)

Examples

```
## Example for deep learning proportional hazards survival model
set.seed(101)
### define model layers
model = dnnmodel(units = c(4, 3, 1), activation = c("elu", "sigmoid", "sigmoid"),
                 input_shape = 3)
x = matrix(runif(15), nrow = 5, ncol = 3)
time = exp(x[, 1])
status = c(1, 0, 1, 1, 1)
fit = deepSurv(Surv(time, status) ~ x, model = model)
```

dnnControl

*Auxiliary function for `dnnFit` `dnnFit`***Description**

`dnnControl` is an auxiliary function for `dnnFit`. Typically only used internally by the `dnn` package, may be used to construct a control argument for the deep learning neural network model to specify parameters such as a loss function.

Usage

```
dnnControl(loss = c("mse", "cox", "bin", "log", "mae"), epochs = 300,
           batch_size = 64, verbose = 0, lr_rate = 0.0001,
           alpha = 0.5, lambda = 1.0, epsilon = 0.01, max.iter = 100,
           censor.group = NULL, weights = NULL)
```

Arguments

<code>loss</code>	loss function for the neural network model, "mse" for mean square error (gaussian glm model), "mae" for mean absolute error, "cox" for the Cox partial likelihood (proportional hazards model), "bin" for cross-entropy (binomial glm model), "log" for log-linear (poisson glm model).
<code>epochs</code>	number of deep learning epochs, default is 30.
<code>batch_size</code>	batch size, default is 64. 'NaN' may be generated if batch size is too small and there is not event in a batch.
<code>lr_rate</code>	learning rate, default is 0.0001.
<code>weights</code>	an optional vector of 'prior weights' to be used in the fitting process. Should be NULL or a numeric vector, default is NULL.
<code>alpha</code>	alpha decay rate for momentum gradient descent, default is 0.5.
<code>lambda</code>	regularization term for dnn weighting parameters, $0.5 * \lambda * W * W$, default is 1.0.
<code>verbose</code>	<code>verbose = 1</code> for print out verbose during the model fit, 0 for not print.
<code>epsilon</code>	epsilon for convergence check, default is <code>epsilon = 0.01</code> .
<code>max.iter</code>	number of maximum iteration, default is <code>max.iter = 100</code> . This is used in the <code>deepAFT</code> function
<code>censor.group</code>	a vector for censoring groups. A KM curve for censoring will be fit for each group. If a matrix is provided, then a Cox model will be used to predict the censoring probability. Used only in the <code>deepAFT</code> function.

Details

`dnnControl` is used in model fitting of "`dnnFit`". Additional loss functions will be added to the library in the future.

Value

This function checks the internal consistency and returns a list of values as input to control model fitting of "dnnFit".

Note

For right censored survival time only

Author(s)

Chen, B. E.

References

Norman, P. and Chen, B. E. (2023). DeepAFAT: A nonparametric accelerated failure time model with artificial neural network. Manuscript to be submitted.

See Also

[deepAFT](#), [deepGLM](#), [deepSurv](#), [dnnFit](#)

Examples

```
## Example for dnnControl
##
# model = dNNmodel()

control = dnnControl(loss='mse')

# can also be used in
# fit = dnnFit(y ~ x, model, control)
# print(fit)
```

dnnFit

Fitting a Deep Learning model with a given loss function

Description

dnnFit is used to train a deep learning neural network model based on a specified loss function.

Usage

```
dnnFit(x, y, model, control)
```

Arguments

x	covariates for the neural network model
y	output (target) value for neural network model
model	the neural network model, see below for details
control	a list of control values, in the format produced by 'dnnControl'. The default value is <code>dnnControl(loss='mse')</code>

Details

The 'dnnFit' function takes the input data, the target values, the network architecture, and the loss function as arguments, and returns a trained model that minimizes the loss function. The function also supports various options for regularization and optimization of the model.

See [dNNmodel](#) for details on how to specify a deep learning model.

Parameters in `dnnControl` will be used to control the model fit process. The loss function can be specified as `dnnControl(loss = "lossFunction")`. Currently, the following loss functions are supported:

'mse': Mean square error loss = $0.5 * \sum(dy^2)$

'cox': Cox partial likelihood loss = $-\sum(\delta * (\hat{y} - \log(S_0)))$

'bin': Cross-entropy = $-\sum(y * \log(p) + (1-y) * \log(1-p))$

'log': Log linear cost = $-\sum(y * \log(\lambda) - \lambda)$

'mae': Mean absolute error loss = $\sum(\text{abs}(dy))$

Additional loss functions will be added to the library in the future.

{ `dnnFit2` } is a C++ version of `dnnFit`, which runs about 20% faster, however, only `loss = 'mse'` and `'cox'` are currently supported.

When the variance for covariance matrix X is too large, please use `xbar = scale(x)` to standardize X.

Value

An object of class "dnnFit" is returned. The `dnnFit` object contains the following list components:

cost	cost at the final epoch.
dW	the gradient at the final epoch $dW = dL/dW$.
fitted.values	predictor value $\mu = f(x)$.
history	a cost history at each epoch.
lp	predictor value $\mu = f(x)$.
logLik	$-2 * \log$ Likelihood = cost.
model	a <code>dNNmodel</code> object.
residuals	raw residual $dy = d \log(L)/d\mu$
dvi	deviance $dvi = dy * dy$

Author(s)

Chen, B. E. and Norman P.

References

- Buckley, J. and James, I. (1979). Linear regression with censored data. *Biometrika*, 66, page 429-436.
- Norman, P. and Chen, B. E. (2019). DeepAFAT: A nonparametric accelerated failure time model with artificial neural network. Manuscript to be submitted.
- Chollet, F. and Allaire J. J. (2017). Deep learning with R. Manning.

See Also

[deepAFT](#), [deepGlm](#), [deepSurv](#), [dnnControl](#)

Examples

```
## Example for dnnFit with MSE loss function to do a non-linear regression
set.seed(101)
### define model layers
model = dNNmodel(units = c(4, 3, 1), activation = c("elu", "sigmoid", "sigmoid"),
                 input_shape = 3)
x = matrix(runif(15), nrow = 5, ncol = 3)
y = exp(x[, 1])
control = dnnControl(loss='mse')
fit = dnnFit(x, y, model, control)
```

dNNmodel

Specify a deep neural network model

Description

{dNNmodel} is an R function to create a deep neural network model that is to be used in the feed forward network { fwdNN } and back propagation { bwdNN }.

Usage

```
dNNmodel(units, activation=NULL, input_shape = NULL, type = NULL,
         N = NULL, Rcpp=TRUE, optimizer = c("momentum", "nag", "adam"))
```

Arguments

units	number of nodes for each layer
activation	activation function
input_shape	the number of columns of input X, default is NULL.
N	the number of training sample, default is NULL.
type	default is "dense", currently only support dense layer.
Rcpp	use Rcpp (C++ for R) to speed up the fwdNN and bwdNN, default is "TRUE".
optimizer	optimizer used in SGD, default is "momentum".

Details

dNNmodel returns an object of class "dNNmodel".

The function "print" (i.e., "print.dNNmodel") can be used to print a summary of the dnn model,

The function "summary" (i.e., "summary.dNNmodel") can be used to print a summary of the dnn model,

Value

An object of class "dNNmodel" is a list containing at least the following components:

units	number of nodes for each layer
activation	activation function
drvfun	derivative of the activation function
params	the initial values of the parameters, to be updated in model training.
input_shape	the number of columns of input X, default is NULL.
N	the number of training sample, default is NULL.
type	default is "dense", currently only support dense layer.

Author(s)

Bingshu E. Chen (bingshu.chen@queensu.ca)

See Also

[plot.dNNmodel](#), [print.dNNmodel](#), [summary.dNNmodel](#), [fwdNN](#), [bwdNN](#), [optimizerSGD](#), [optimizerNAG](#),

Examples

```
### To define a dnn model
model = dNNmodel(units = c(8, 6, 1), activation = c("relu", "sigmoid", "sigmoid"),
  input_shape = c(3))
```

fwdNN

Feed forward and back propagation for dnn Models

Description

{fwdNN} is an R function for feed forward network.

Usage

```
fwdNN(X, model)
#
# to calculate a feed forward model
#
```

Arguments

`X` For "dNNmodel", X is a design matrix of dimension $n * p$.
`model` a model return from dNNmodel function.

Details

'cache' is the cache of each input layer, will be used in the bwdNN function.

Value

The function fwdNN return a list containing at least the following components:

`cache` a list contains the values of each output layer after activation function transformation and adding the intercept term (i.e. the bias term). The intercept does not add to the output layer in the cache.

Author(s)

Bingshu E. Chen (bingshu.chen@queensu.ca)

See Also

[bwdNN](#), [plot.dNNmodel](#), [print.dNNmodel](#), [summary.dNNmodel](#),

Examples

```
### define a dnn model, calculate the feed forward network
model = dNNmodel(units = c(8, 6, 1), activation = c("elu", "sigmoid", "sigmoid"),
                 input_shape = 3)

### feed forward with a dummy x matrix
x = matrix(runif(15), nrow = 5, ncol = 3)
cache = fwdNN(x, model)
```

hyperTuning

A function for tuning of the hyper parameters

Description

{ hyperTuning } is a tuning tool to find the optimal hyper parameter for the ANN model.

Usage

```

hyperTuning(x, y, model, ER = c("cindex", "mse"),
            method = c('BuckleyJames', 'ipcw', 'transform', 'deepSurv'),
            lower = NULL, upper = NULL, node = FALSE,
            K = 5, R = 25)
### additional function used in hyperTuning is cross-validation prediction error
#
# CVpredErr(x, y, model, control, method)
#

```

Arguments

x	Covariates for the deep neural network model
y	Surv object for the deep neural network model
model	A deep neural network model, created by function <code>dNNmodel()</code> .
ER	Prediction error measurement to be used in the cross validation, can be either a concordance index (cindex) or a mean square error (mse), default is cindex
method	Methods to handle censoring data in deep AFT model fit, 'BuckleyJames' for the Buckley and James method, 'ipcw' for the inverse probability censoring weights method. 'transform' for the transformation method based on book of Fan and Gijbels (1996, page 168). 'deepSurv' for the deepSurv model(Katzman, 2017)
node	Tuning the number of nodes in each hidden layer, default is FALSE
K	Number of folders of the cross-validation, default is K = 5.
lower, upper	Bounds on the hyper parameters for the deep learning method. If NULL, then the default value for lower = <code>dnnControl(alpha = 0.5, lambda = 1.0, lr_rate = 0.0001)</code> , upper = <code>dnnControl(alpha = 0.97, lambda = 10, lr_rate = 0.001)</code> .
R	Number of random sample draw from the hyper parameter space, default is R = 25.

Details

A random search method is used to optimal hyper parameter (Bergstra and Bengio, 2012). The function { CVpredErr} will be call to calculate the cross-validation prediction error for the given x and y with the specified method from the input argument.

Value

A list of "model" and "dnnControl" is returned. The list contains at least the following components,

model	The "model" contains the optimal number of nodes for each hidden layer in the model specified by <code>dNNmodel</code>
control	The "control" contains the optimal tuning parameters with list components the same as those created by <code>dnnControl</code>

Author(s)

Chen, B. E. (chenbe@queensu.ca)

References

Bergstra, J. and Bengio, Y. (2012). Random search for hyper-parameter optimization. The Journal of Machine Learning Research. 13, page 281-305.

See Also

[deepAFT](#), [deepGLM](#), [deepSurv](#), [dnnFit](#)

Examples

```
### Tuning the hyper parameter for a deepAFT model:
#### cross-validation take a long time to run.

set.seed(101)
### define model layers
model = dNNmodel(units = c(4, 3, 1), activation = c("elu", "sigmoid", "sigmoid"),
                 input_shape = 3)
x = matrix(runif(45), nrow = 15, ncol = 3)
time = exp(x[, 1])
status = rbinom(15, 1, 0.5)
y = Surv(time, status)
ctl = dnnControl(epochs = 30)
hyperTuning(x, y, model, method = "BuckleyJames", K = 2, R = 2, lower = ctl)
```

ibs

Calculate integrated Brier Score for deepAFT

Description

The function `ibs` is used to calculate integrated Brier Score for deepAFT.

Usage

```
ibs(object, ...)
### To calculate Brier score for the original fitted data
## Default S3 method:
ibs(object, ...)
### To calculate Brier score for new data with new outcomes
## S3 method for class 'deepAFT'
ibs(object, newdata=NULL, newy = NULL, ...)
```

Arguments

<code>object</code>	the results of a deepAFT fit.
<code>newdata</code>	optional argument, if no null, new data and new y will be used for calculation.
<code>newy</code>	optional argument, used together with new data.
<code>...</code>	other unused arguments.

Details

ibs is called to calculate integrate Brier score for the deepAFT model [deepAFT](#).

Value

A list contains the integrate Brier score and the Brier score is returned:

ibs	Integerate Brier score
bs	Brier score

Author(s)

Bingshu E. Chen

See Also

[deepAFT](#)

 msePICW

Mean Square Error (mse) for a survival Object

Description

Compute Mean Square Error (mse) values for a survival object

Usage

```
## S3 method for class 'deepAFT'
mseIPCW(object, newdata, newy)
```

Arguments

object	the results of a model fit using a deepAFT or a survreg function.
newdata	optional new data at which to do predictions. If absent, predictions are for the dataframe used in the original fit.
newy	optional new outcome variable y.

Details

predict is called to predict object from a deepAFT [deepAFT](#) or a survreg model.

IPCW method is used to calculate the mean square error for censored survival time.

Value

mseIPCW returns the mse for the predicted survival data.

Author(s)

Bingshu E. Chen

See Also

The default method for predict [predict](#), [deepAFT](#), [survfit.dSurv](#)

optimizerSGD

Functions to optimize the gradient descent of a cost function

Description

Different type of optimizer functions such as SGD, Momentum, AdamG and NAG.

Usage

```
optimizerMomentum(V, dW, W, alpha = 0.63, lr = 1e-4, lambda = 1)
```

Arguments

V	Momentum $V = \alpha * V - lr * (dW + \lambda * W)$; $W = W + V$. NAG $V = \alpha * (V - lr * (dW + \lambda * W))$; $W = W + V - lr * (dW + \lambda * W)$
dW	derivative of cost with respect to W, can be found by $dW = bwdNN2(dy, cache, model)$,
W	weights for DNN model, optimized by $W = W + V$
alpha	Momentum rate $0 < \alpha < 1$, default is $\alpha = 0.5$.
lr	learning rate, default is $lr = 0.001$.
lambda	regulation rate for cost $+ 0.5 * \lambda * \ W\ $, default is $\lambda = 1.0$.

Details

For SGD with momentum, use

```
V = 0; obj = optimizerMomentum(V, dW, W); V = obj$V; W = obj$W
```

For SDG with MAG

```
V = 0; obj = optimizerNAG(V, dW, W); V = obj$V; W = obj$W
```

Value

return and updated W and other parameters such as V, V1 and V2 that will be used on SGD.

Author(s)

Bingshu E. Chen

See Also

[activation](#), [bwdNN](#), [fwdNN](#), [dNNmodel](#), [dnnFit](#)

plot

Plot methods in dnn package

Description

Plot function for plotting of R objects in the dnn package.

Several different type of plots can be produced for the deep learning mdels. Plot method is used to provide a summary of outputs from "deepAFT", "deepGLM", "deepSurv" and "dnn".

Use "methods(plot)" and the documentation for these for other plot methods.

Usage

```
## S3 method for class 'dNNmodel'  
plot(x, ...)  
## S3 method for class 'deepAFT'  
plot(x, type = c("predicted", "residuals", "baselineKM"), ...)
```

Arguments

x	a class of "dNNmodel".
type	type of plot in deepAFT object, "predicted" to plot the linear predicted values, "residuals" to plot residuals, "baselineKM" to plot baseline Kaplan-Meier survival curve.
...	other options used in plot().

Details

plot.deepAFT is called to plot the fitted deep learning AFT model.

plot.dNNmodel is called to plot fitted dnn model

The default method, plot.default has its own help page. Use methods("plot") to get all the methods for the plot generic.

Value

No return value, called to plot a figure.

Author(s)

Bingshu E. Chen

See Also

The default method for plot [plot.default.glm](#)

predict *Predicted Values for a deepAFT Object*

Description

Compute predicted values for a deepAFT object

Usage

```
## S3 method for class 'deepAFT'
## S3 method for class 'dSurv'
predict(object, newdata, newy=NULL, ...)
```

Arguments

object	the results of a model fit using the deepAFT function.
newdata	optional new data at which to do predictions. If absent, predictions are for the dataframe used in the original fit.
newy	optional new outcome variable y.
...	other options used in predict().

Details

predict.dSurv is called to predict object from the deepAFT or deepSurv model [deepAFT](#).

The default method, predict has its own help page. Use methods("predict") to get all the methods for the predict generic.

Value

predict.dSurv returns a list of predicted values, prediction error and residuals.

lp	linear predictor of $\beta(w)*Z$, where $\beta(w)$ is the fitted regression coefficient and Z is covariance matrix.
risk	risk score, $\exp(lp)$. When new y is provided, both lp and risk will be ordered by survival time of the new y.
cumhaz	cumulative hazard function.
time	time for cumulative hazard function. Time from new y will be used is provided

Author(s)

Bingshu E. Chen

See Also

The default method for predict [predict](#), [deepAFT](#), [survfit.dSurv](#)

print	<i>print a summary of fitted deep learning model object</i>
-------	---

Description

print is used to provide a short summary of outputs from [deepAFT](#), [deepSurv](#), [deepGLM](#), and [dNNmodel](#).

Usage

```
## S3 method for class 'deepAFT'
print(x, ...)
## S3 method for class 'summary.deepAFT'
print(x, ...)
## S3 method for class 'deepAFT'
summary(object, ...)

## S3 method for class 'dNNmodel'
print(x, ...)
## S3 method for class 'dNNmodel'
summary(object, ...)
```

Arguments

x	a class returned from deepAFT , deepSurv , deepGLM model fit or a dNNmodel
object	a class of deepAFT object
...	other options used in <code>print()</code>

Details

`print.deepAFT` is called to print object or summary of object from the deep learning AFT models [deepAFT](#). `summary(fit)` provides detail summary of 'deepAFT' model fit, including predictors, baseline survival function for $T_0=T/\exp(\mu)$, and martingale residuals for the fitted model.

`print.dNNmodel` is called to print object or summary of object from the [dNNmodel](#).

The default method, `print.default` has its own help page. Use `methods("print")` to get all the methods for the `print` generic.

Value

An object of class "summary.deepAFT" is returned. The object contains the following list components:

location	location parameter $\exp(\mu)$, to predice the mean value of survival time.
sfit	survfit object of the baselie survival function of $T_0=T/\exp(\mu)$.
cindex	Concordance index of the fitted deepAFT model.
resid	martingle residuals of the fitted deepAFT model.
method	the model used to fit the deepAFT model.

Author(s)

Bingshu E. Chen

See Also

The default method for print `print.default`. Other methods include `survreg`, `deepAFT`, `summary`

residuals

Calculate Residuals for a deepAFT Fit.

Description

Calculates martingale, deviance or Cox-Snell residuals for a previously fitted (deepAFT) model.

Usage

```
## S3 method for class 'deepAFT'
## S3 method for class 'dSurv'
residuals(object, type = c("martingale", "deviance", "coxSnell"), ...)
```

Arguments

object	the results of a (deepAFT) fit.
type	character string indicating the type of residual desired. Possible values are "martingale", "deviance". Only enough of the string to determine a unique match is required.
...	other unused arguments.

Details

`residuals.deepAFT` is called to compute baseline survival function $S_{T0}(t)$ from the deepAFT model `deepAFT`, where $T0 = T/\exp(\mu)$, or $\log(T) = \log(T) - \mu$.

The default method, `residuals` has its own help page. Use `methods("residuals")` to get all the methods for the residuals generic.

Value

For martingale and deviance residuals, the returned object is a vector with one element for each subject. The row order will match the input data for the original fit.

See `residuals` for more detail about other output values.

Note

For deviance residuals, the status variable may need to be reconstructed.

Author(s)

Bingshu E. Chen

See Also

The default method for residuals [residuals](#), [predict.dSurv](#), [survfit.dSurv](#), and [deepAFT](#).

rsurv

*The Survival Distribution***Description**

Density, distribution function, quantile function and random variable generation for a survival distribution with a provided hazard function or cumulative hazard function

Usage

```
dsurv(x, h0 = NULL, H0 = function(x){x}, log=FALSE)
psurv(q, h0 = NULL, H0 = function(x){x}, low.tail=TRUE, log.p=FALSE)
qsurv(p, h0 = NULL, H0 = function(x){x}, low.tail=TRUE)
rsurv(n, h0 = NULL, H0 = function(x){x})
rcoxph(n, h0 = NULL, H0 = function(x){x}, lp = 0)
```

Arguments

x, q	vector of quantiles.
p	vector of probabilities.
n	number of observations.
h0	hazard function, default is h0 = NULL.
H0	cumulative hazard function, default is H0(x) = x.
lp	linear predictor for rcoxph, H(x) = H0(x)exp(lp).
log, log.p	logical; if TRUE, probabilities p are give as log(p).
low.tail	logical; if TRUE, probabilities are P[X < or = x] otherwise, S(x) = P[X>x].

Details

If { h0 } or { H0 } are not specified, they assume the default values of h0(x) = 1 and H0(x) = x, respectively.

The survival distribution function is given by,

$$S(x) = \exp(-H0(x)),$$

where H0(x) is the cumulative hazard function. Only one of h0 or H0 can be specified, if h0 is given, then H0(x) = integrate(h0, 0, x, subdivisions = 500L)

To generate Cox PH survival time, use

$$u = \exp(-H(t)*\exp(lp))$$

then, $-\log(u)*\exp(-lp) = H(t)$. Find t such that $H(t) = -\log(u)\exp(-lp)$.

Value

{ dsurv } gives the density $h(x)/S(x)$, { psurv } gives the distribution function, { qsurv } gives the quantile function, { rsurv } generates random survival time, and { rcoxph } generates random survival time with Cox proportional hazards model.

The length of the result is determined by n for rsurv and rcoxph.

Author(s)

Bingshu E. Chen

References

Johnson, N. L., Kotz, S. and Balakrishnan, N. (1995). Continuous Univariate Distributions, volume 1. Wiley, New York.

See Also

[Distributions](#) for other standard distributions, including [dweibull](#) for the Weibull distribution.

Examples

```
#### use qsurv to generate quantiles for weibull distribution
H1 = function(x) x^3
qsurv(seq(0.1, 0.9, 0.2), H0 = H1) ### shall be the same as
qweibull(seq(0.1, 0.9, 0.2), 3)
#### to get random survival time from the cumulative hazard function H1(t)
rsurv(15, H0 = H1)
```

survfit

Compute a Survival Curve from a deepAFT or a deepSurv Model

Description

Computes the predicted survival function of a previously fitted deepAFT or deepSurv model.

Usage

```
## S3 method for class 'deepAFT' or 'deepSurv'
## S3 method for class 'dSurv'
survfit(formula, se.fit=TRUE, conf.int=.95, ...)
```

Arguments

formula	a deepAFT or deepSurv fit object.
se.fit	a logical value indicating whether standard errors shall be computed. Default is TRUE
conf.int	the level for a two-sided confidence interval on the survival curve. Default is 0.95
...	other unused arguments.

Details

survfit.dSurv is called to compute baseline survival function $S_{T0}(t)$ from the deepAFT model [deepAFT](#), where $T0 = T/\exp(\mu)$, or $\log(T) = \log(T) - \mu$.

For the deepSurv model [deepAFT](#), survfit.dSurv evaluates the Nelson-Aalen estimate of the baseline survival function.

The default method, survfit has its own help page. Use `methods("survfit")` to get all the methods for the survfit generic.

Value

survfit.deepAFT returns a list of predicted baseline survival function, cumulative hazard function and residuals.

surv	Predicted baseline survival function for $T0=T/\exp(\mu)$.
cumhaz	Baseline cumulative hazard function, $-\log(\text{surv})$.
hazard	Baseline hazard function.
varhaz	Variance of the baseline hazard.
residuals	Martingale residuals of the (deepAFT) model.
std.err	Standard error for the cumulative hazard function, if <code>se.fit = TRUE</code> .

See [survfit](#) for more detail about other output values such as upper, lower, conf.type. Confidence interval is based on log-transformation of survival function.

Author(s)

Bingshu E. Chen

See Also

The default method for survfit [survfit](#), [predict.dSurv](#)

Index

- * **Back propagation**
 - activation, 3
 - bwdNN, 5
 - * **Cox PH random variable**
 - rsurv, 27
 - * **Deep Neural Networks**
 - dnn-package, 2
 - * **Deep Neural Network**
 - activation, 3
 - bwdNN, 5
 - dNNmodel, 16
 - fwdNN, 17
 - * **Feed forward**
 - activation, 3
 - fwdNN, 17
 - * **Hyper parameter**
 - hyperTuning, 18
 - * **IPCW**
 - msePICW, 21
 - * **Integrated Brier Score**
 - ibs, 20
 - * **MSE**
 - msePICW, 21
 - * **Survival distribution**
 - rsurv, 27
 - * **activation function**
 - activation, 3
 - * **dNNmodel**
 - deepAFT, 6
 - * **deepAFT**
 - deepAFT, 6
 - hyperTuning, 18
 - plot, 23
 - print, 25
 - * **deepGLM**
 - deepGLM, 9
 - plot, 23
 - print, 25
 - * **deepSurv**
 - deepSurv, 11
 - hyperTuning, 18
 - plot, 23
 - print, 25
 - * **dnnControl**
 - deepAFT, 6
 - * **dnnFit**
 - dnnControl, 13
 - dnnFit, 14
 - * **dnn**
 - deepGLM, 9
 - deepSurv, 11
 - * **optimizer AdamG**
 - optimizerSGD, 22
 - * **optimizer Momentum**
 - optimizerSGD, 22
 - * **optimizer NAG**
 - optimizerSGD, 22
 - * **optimizer SDG**
 - optimizerSGD, 22
 - * **plot**
 - plot, 23
 - * **predict**
 - predict, 24
 - * **print**
 - print, 25
 - * **residuals**
 - residuals, 26
 - * **summary**
 - plot, 23
 - print, 25
 - * **survfit**
 - survfit, 28
- activation, 3, 22
- bwdCheck (bwdNN), 5
- bwdNN, 3, 4, 5, 17, 18, 22
- bwdNN2 (bwdNN), 5

coxph, 3
 CVpredErr (hyperTuning), 18

 deepAFT, 3, 6, 10, 12, 14, 16, 20–22, 24–27, 29
 deepGLM, 3, 9, 14, 20, 25
 deepGlm, 12, 16
 deepGlm (deepGLM), 9
 deepSurv, 3, 11, 14, 16, 20, 25
 delu (activation), 3
 didu (activation), 3
 Distributions, 28
 dlrelu (activation), 3
 dnn (dnn-package), 2
 dnn-doc (dnn-package), 2
 dnn-package, 2
 dnnControl, 13, 15, 16, 19
 dnnFit, 13, 14, 14, 20, 22
 dnnFit2 (dnnFit), 14
 dNNmodel, 3, 4, 6, 10, 15, 16, 19, 22, 25
 drelu (activation), 3
 dsigmoid (activation), 3
 dsurv (rsurv), 27
 dtanh (activation), 3
 dweibull, 28

 elu (activation), 3

 fwdNN, 3, 4, 6, 17, 17, 22
 fwdNN2 (fwdNN), 17

 glm, 3, 10, 23

 hyperTuning, 18

 ibs, 20
 ibs.deepAFT, 8
 idu (activation), 3

 lrelu (activation), 3

 mseIPCW (msePICW), 21
 msePICW, 21

 optimizerAdamG (optimizerSGD), 22
 optimizerMomentum (optimizerSGD), 22
 optimizerNAG, 4, 17
 optimizerNAG (optimizerSGD), 22
 optimizerSGD, 4, 17, 22

 plot, 23

 plot.default, 23
 plot.dNNmodel, 6, 17, 18
 predict, 22, 24, 24
 predict.deepGlm, 10
 predict.deepGlm (deepGLM), 9
 predict.dNNmodel (fwdNN), 17
 predict.dSurv, 27, 29
 print, 25
 print.deepAFT, 8
 print.deepSurv, 10, 12
 print.default, 26
 print.dNNmodel, 6, 17, 18
 psurv (rsurv), 27

 qsurv (rsurv), 27

 rcoxph (rsurv), 27
 relu (activation), 3
 residuals, 26, 26, 27
 residuals.deepGlm (deepGLM), 9
 rSurv (rsurv), 27
 rsurv, 27

 sigmoid (activation), 3
 summary, 26
 summary.deepAFT (print), 25
 summary.deepGlm (deepGLM), 9
 summary.deepSurv (deepSurv), 11
 summary.dNNmodel, 6, 17, 18
 summary.dNNmodel (print), 25
 survfit, 28, 29
 survfit.dSurv, 22, 24, 27
 survival, 3
 survreg, 8, 12, 26